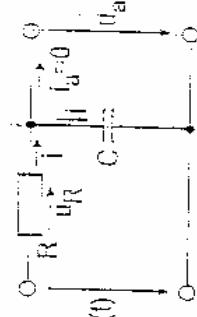
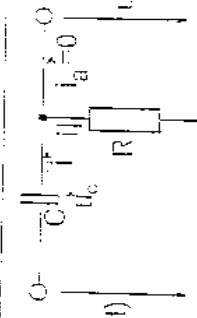


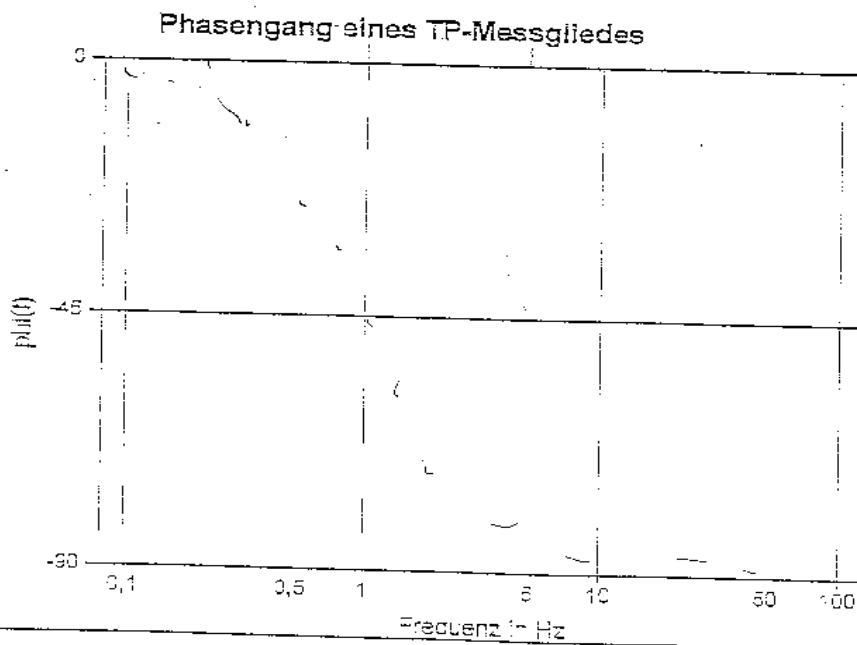
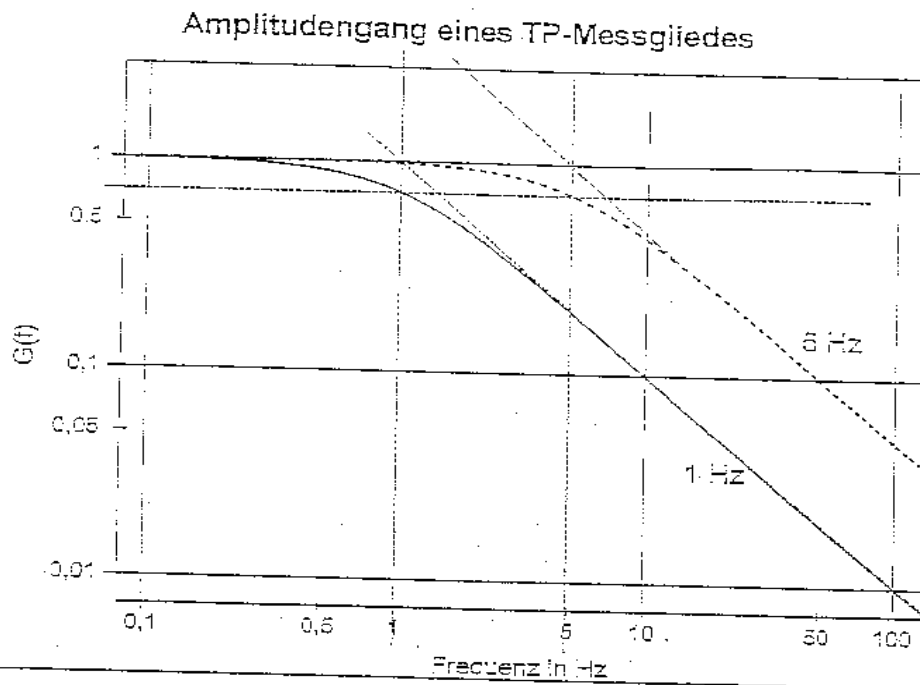
2.1 Frequenzverhalten von Sensoren

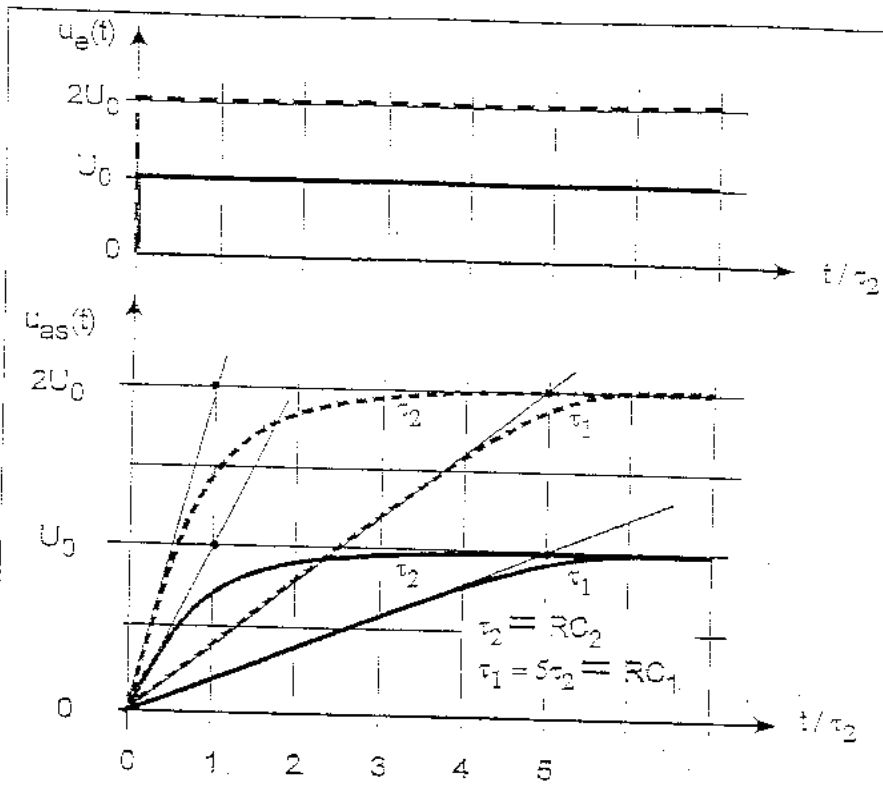
	Messglied Typ A	Messglied Typ B
a) $G = \frac{U_a}{U_e} =$	$\frac{Z_C}{R + Z_C} = \frac{1}{1 + \frac{R}{Z_C}} = \frac{1}{1 + j\omega RC}$	$\frac{R}{R + Z_C} = \frac{1}{1 + \frac{Z_C}{R}} = \frac{j\omega RC}{1 + j\omega RC}$
b) $\operatorname{Re}\{G(\omega_g)\} = \operatorname{Im}\{G(\omega_g)\}$ $\operatorname{Re}\{G(f_g)\} = \operatorname{Im}\{G(f_g)\}$	$\omega_g = \frac{1}{RC} \quad f_g = \frac{1}{2\pi RC}$	$\omega_g = \frac{1}{RC} \quad f_g = \frac{1}{2\pi RC}$
c) $G = \frac{U_a}{U_e} =$	$\frac{1}{1 + j\omega/\omega_g} = \frac{1}{1 + jf/f_g}$	$\frac{\omega/\omega_g}{1 + j\omega/\omega_g} = \frac{f/f_g}{1 + jf/f_g}$
d) $G = \gamma = \sqrt{\operatorname{Im}^2 + \operatorname{Re}^2} =$	$\frac{1}{\sqrt{1 + (\omega/\omega_g)^2}} = \frac{1}{\sqrt{1 + (f/f_g)^2}}$	$\frac{\omega/\omega_g}{\sqrt{1 + (\omega/\omega_g)^2}} = \frac{f/f_g}{\sqrt{1 + (f/f_g)^2}}$
e) Phasengang $\varphi = \operatorname{arctg} \frac{\operatorname{Im}}{\operatorname{Re}}$	$\operatorname{arctg}(f/f_g)$	$\operatorname{arctg}\left(\frac{1}{f/f_g}\right)$

	Messglied Typ A	Messglied Typ B
e)	$G(f_2)/G(0) = 1/\sqrt{2} = 0,707$	$1/\sqrt{2} = 0,707$
f)	<p>in der Regel unzulässig grosse Fehler: Amplitudenfehler ca 30% Phasenfehler 45°</p>	<p>in der Regel unzulässig grosse Fehler: Amplitudenfehler ca 30% Phasenfehler 45°</p>
g)	<p>Grenzfrequenzen zahlenmässig</p> <p>$0,16 \text{ M}\Omega; 1 \mu\text{F} \rightarrow \tau_1 = RC_1 = 0,16 \text{ s} \rightarrow f_{g1} = 1 \text{ Hz}$ $0,16 \text{ M}\Omega; 200 \text{ pF} \rightarrow \tau_2 = RC_2 = \frac{1}{5} \cdot 0,16 \text{ s} \Rightarrow f_{g2} = 5 \text{ Hz}$</p>	<p>$0,16 \text{ M}\Omega; 1 \mu\text{F} \rightarrow \tau_1 = RC_1 = 0,16 \text{ s} \rightarrow f_{g1} = 1 \text{ Hz}$ $0,16 \text{ M}\Omega; 200 \text{ pF} \rightarrow \tau_2 = RC_2 = \frac{1}{5} \cdot 0,16 \text{ s} \Rightarrow f_{g2} = 5 \text{ Hz}$</p>
h)	siehe separate Diagramme	siehe separate Diagramme
i)		
j)	<p>Schaltbild</p> <p>$u_R + u_a = u_e ; i_R = i_C = i ; u_R = iR ;$ $u_a = u_C = \frac{1}{C} \int i dt ; i = C \dot{u}_a$ $\Rightarrow RC \dot{u}_a + u_a = u_e$</p>	<p>$u_C + u_a = u_e ; i_R = i_C = i ; u_a = iR$ $u_C = \frac{1}{C} \int i dt ; \rightarrow \int \frac{u_a}{R} dt + u_a = u_e$ $\Rightarrow RC \dot{u}_a + u_a = i_e RC$</p>
k)	DGL	

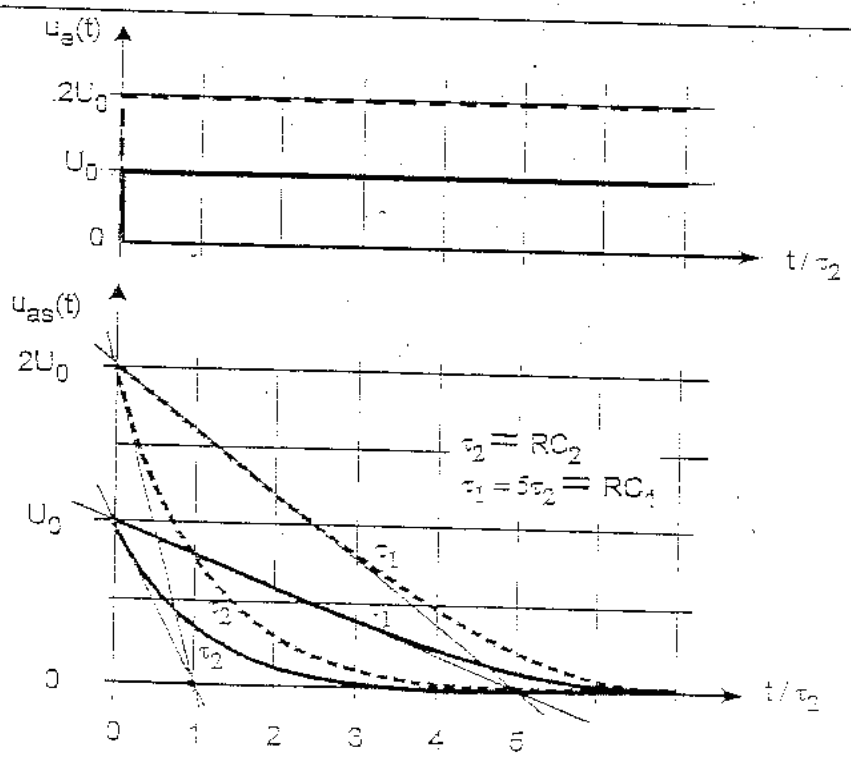
	Messglied Typ A	Messglied Typ B
j) Lösen der DGL. von \dot{f} für Sprung von $0V \rightarrow U_0$	$u_{as}(t) = U_0(1 - e^{-t/\tau}) \quad \text{mit } \tau = RC$ $h(t) = u_{as}(t)/U_0 = (1 - e^{-t/\tau})$	$u_{as}(t) = U_0 e^{-t/\tau} \quad \text{mit } \tau = RC$ $h(t) = u_{as}(t)/U_0 = e^{-t/\tau}$
k)	siehe separate Diagramme	siehe separate Diagramme
h) Betrachtung im Zeitbereich Betr. im Frequenzbereich	\Rightarrow Tiefpaßverhalten, da $G(f \ll f_0) \approx 1$; \Rightarrow Integrierer, da $G(f \gg f_0) \approx 1/j\omega$	\Rightarrow Hochpaßverhalten, da $G(f \gg f_0) \approx 1$; \Rightarrow Differenzierer, da $G(f \ll f_0) \approx j\omega$

2.1 Frequenzverhalten von Sensoren



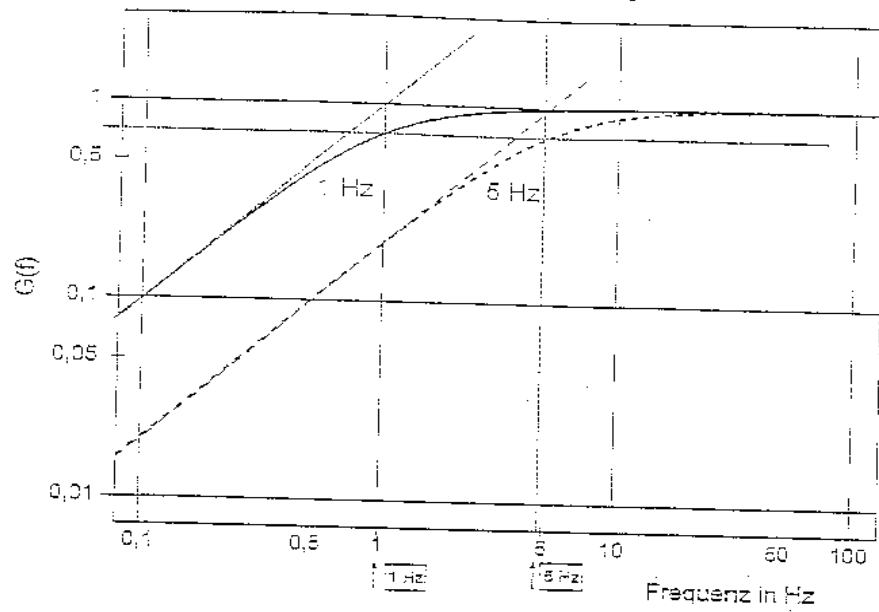


Sprungantworten eines TP-Messgliedes

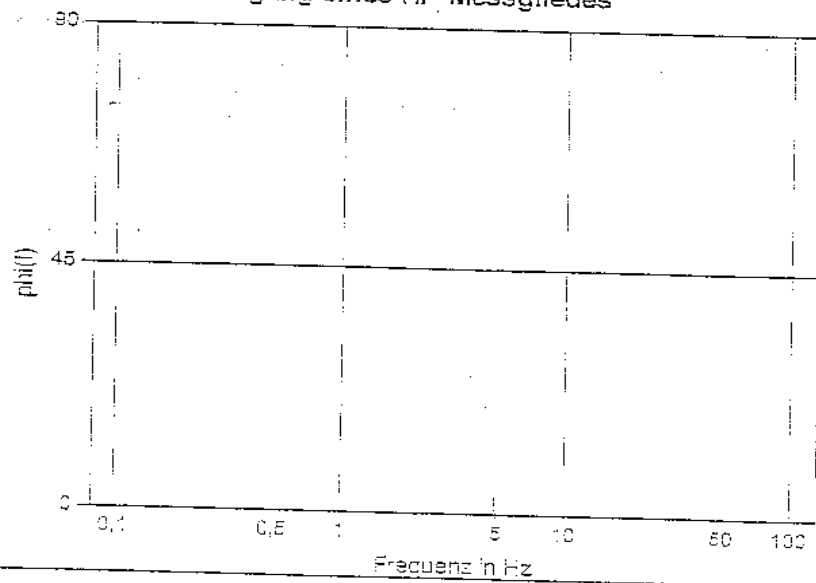


Sprungantworten eines HP-Messgliedes

Amplitudengang eines HP-Messgliedes



Phasengang eines HP-Messgliedes



2.2 komplexer Spannungsteiler

allg.
$$\frac{\underline{U}_2}{\underline{U}_1} = \frac{\underline{Z}_2}{\underline{Z}_1 + \underline{Z}_2} = \frac{1}{1 + \frac{\underline{Z}_1}{\underline{Z}_2}}$$

a) $\underline{Z}_1 = R_1; \underline{Z}_2 = R_2 \parallel C_2 = \frac{R_2}{1 + j\omega R_2 C_2} \Rightarrow \frac{\underline{U}_2}{\underline{U}_1} = \frac{1}{1 + \frac{R_1}{R_2}(1 + j\omega R_2 C_2)}$

b) $\underline{Z}_1 = R_1 \parallel C_1 = \frac{R_1}{1 + j\omega R_1 C_1}; \underline{Z}_2 = R_2 \parallel C_2 = \frac{R_2}{1 + j\omega R_2 C_2} \Rightarrow \frac{\underline{U}_2}{\underline{U}_1} = \frac{1}{1 + \frac{R_1}{R_2} \frac{1 + j\omega R_2 C_2}{1 + j\omega R_1 C_1}}$

c) $\frac{\underline{U}_2}{\underline{U}_1} = \frac{1}{1 + \frac{R_1}{R_2}} = g(\omega)$ für $\frac{1 + j\omega R_2 C_2}{1 + j\omega R_1 C_1} = 1 \Rightarrow R_1 C_1 = R_2 C_2$